

## APPENDIX B - MOUNT SPECIFIC DATA

### For

### Sat-LiteTechnologies

### 1841 Circular Pol Antenna

This appendix describes RC3000 functions unique for the Sat-LiteTech model 1841 Circular pol with provisions for linear pol mount.

Revision History. Date: 14 January 2014 - Software Version: 1.60

#### 1.1 Manual Organization

This appendix is provided as a supplement to the baseline RC3000 manual. Differences between this version and the operation described in the baseline RC3000 manual are noted on a paragraph by paragraph basis.

#### 1.2 RC3000 Features

All RC3000 features described in the baseline manual are present with this version. The unique features of this version of the RC3000 are:

- 1) Final elevation stow position will be determined by monitoring elevation drive current.

**Hardware Configuration.** This mount version will be mechanized using the RC3000A hardware configuration.

#### Software Configuration.

DESIGNATION	MODEL
JY	1841 Circular Pol with Linear Pol provision

#### 1.3.3 Operational Overview

Operations of the JY version are almost identical to that described in the baseline manual. Differences will be noted in the appropriate paragraphs.

## 2.0 INSTALLATION

### 2.1.4 Electronic Clinometer

The inclinometer should be rigged with the backstructure vertical.

## 2.3 Calibration

Calibration steps defined in the RC3000 baseline manual should all be performed.

Additional unique calibration steps for the JY mount are defined in the following paragraphs.

### 2.3.2 Elevation Calibration

#### Elevation Reference Voltage

A correctly set elevation reference voltage should result in a displayed elevation angle of 17.8 degrees when the face of the reflector is plumb.

#### Define Elevation STOW current limit

In MANUAL mode drive elevation down through the STOW switch and incrementally increase the STW\_AMP value until the desired amount of elevation pre-load is achieved.

**CAUTION: be extremely careful while incrementing the STW\_AMP value. Too high of a value will allow the elevation drive to pre-load the dish with potentially damaging force.**

### 3.0 Detailed Operation

#### 3.2.1 Manual Mode.

AZIM: 0.0 STOW	CH4: 50	MANUAL
ELEV: -42.5 DOWN	SAT: TELSTAR	402
POL: 30.0 V	SPD: FAST	CST
<0-9>JOG ANTENNA	<MODE>MENU	14:25:47

#### CH4:

The JY version allows for a fourth signal channel to be monitored. The Scroll/Dn key will allow the user to scroll through RF/SS1/SS2/CH4. CH4 is the channel that will be used to monitor elevation drive current. NOTE: below the DOWN limit, the display will be forced to CH4 to ensure that the appropriate signal is being monitored at the STOW limit.

When the elevation stow switch is first encountered, the limit display will indicate "stow" vs. "STOW". The display will change to "STOW" when either the stow current limit has been reached or the stow timeout value (15 seconds) has expired.

**NOTE: after reaching STOW, elevation must be driven above the stow switch to reinitialize the stow timeout.**

#### 3.2.2.2 Stow

After sensing the elevation stow switch, monitoring of the elevation drive current will begin. When the elevation drive current reaches the value specified by the STW\_AMP configuration item (3.3.1.3.10), the stow operation will stop. This current monitoring is intended to allow the antenna to be "loaded" firmly into the elevation stow pads.

The stow operation will also cease if a timeout value is reached after the stow switch is sensed but before the current limit is sensed. This timeout condition is provided as a backup to the current sensing mechanism.

#### 3.3.1.3.10 Stow & Deploy Postions

**STW\_AMP: ELEV STOW CURRENT LIMIT <0.0-9.9 AMPS>**

For the JY version, the amount of elevation drive current used to "preload" the antenna into its stow pads may be specified.

This configuration replaces the EL\_TIME item normally shown in this screen.

#### 3.3.1.2 Reset Defaults

The following table supplies the default configuration item values for this mount model.

Space has also been provided to record installation specific changes to the configuration items. Note: recording of installation specific changes to defaults may prove valuable when trying to restore system configuration.

CONFIGURATION ITEM	JY					INSTALL VALUE
<b>SYSTEM DEFINITION</b>						
Antenna_size_cm	180					
GPS	1					
COMP	2					
MODE	2					
WAVE	0					
<b>ELEVATION CALIBRATION</b>						
Zero Voltage	1.69					
Elev_offset	0.0					
Up_elev_limit	90					
Down_elev_limit	5					
Elevation_Scale_Factor	50.00					
Elevation_look_configuration	1					
<b>AZIMUTH CALIBRATION</b>						
Reference_voltage	2.50					
Azim_Scale_Factor	783.33					
Fluxgate_offset	0.0					
ccw_azim_limit	192					
Cw_azim_limit	192					
<b>POLARIZATION CAL</b>						
Zero Voltage	2.50					
Polarization_Offset	0.0					
CW Polarization Limit	90.0					
CCW Polarization Limit	90.0					
Pol_Scale_Factor	39.58					
Polarization_type	2					
H/V_Reference	0					
Default Horizontal Position	0.0					
Default Vertical Position	90.0					
Pol_Automove_Enable	1					
<b>SIGNAL PARAMETERS</b>						
RF_Lock	0					
RF_Time	0.1					
Channel 1 Polarity	1					
Channel 1 Threshold	100					
Channel 1 Delay	0.1					
Channel 1 Lock Type	0					
Channel 2 Polarity	1					
Channel 2 Threshold	100					
Channel 2 Delay	0.1					
Channel 2 Lock Type	2					

CONFIGURATION ITEM	JY					INSTALL VALUE
<b>AUTOPEAK</b>						
Autopeak Enabled	0					
Signal Source	2					
RF Band	1					
Spiral Search AZ Limit	3					
Spiral Search EL Limit	3					
Spiral Signal Threshold	200					
Scan Range Limit	8					
Scan Signal Threshold	200					
Tilt	0					
<b>AZIMUTH POT DRIVE</b>						
Fast/Slow Threshold	2.5					
Maximum Position Error	0.2					
Coast Threshold	0.1					
Maximum Retry Count	3					
<b>AZIMUTH PULSE DRIVE</b>						
Pulse Scale Factor	5308					
CW Pulse Limit	64000					
CCW Pulse Limit	1000					
Fast/Slow Threshold	50					
Maximum Position Error	0					
Coast Threshold	3					
Maximum Retry Count	3					
<b>AZIM DRIVE MONITORING</b>						
Jam Slop	1					
Runaway Slop	400					
Fast Deadband	1000					
Slow Deadband	500					
<b>ELEV POT DRIVE</b>						
Fast/Slow Threshold	3.0					
Maximum Position Error	0.2					
Coast Threshold	0.4					
Maximum Retry Count	3					
<b>ELEV PULSE DRIVE</b>						
Pulse Scale Factor	1151					
UP Pulse Limit	64000					
Down Pulse Limit	100					
Fast/Slow Threshold	200					
Maximum Position Error	0					
Coast Threshold	3					
Maximum Retry Count	3					
<b>ELEV DRIVE MONITORING</b>						
Jam Slop	1					
Runaway Slop	200					
Fast Deadband	1000					
Slow Deadband	500					

